

PETE FAN

Electrical and Computer Engineering

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github.com/PaperFanz

paperfanz.github.io

EDUCATION

B.S. Electrical and Computer Engineering

University of Texas at Austin

Aug 2018 - May 2021

GPA: 3.91

Relevant Coursework: Computer Architecture, Embedded Systems, Operating Systems, Digital Image Processing, Algorithms, Concurrent and Distributed Systems*, Graduate Advanced MCU Systems*

* indicates future coursework

PROFESSIONAL EXPERIENCE

Undergraduate Research Assistant

Nuclear and Applied Robotics Group

April 2019 - Present

Austin, Texas U.S.A.

- Architected an IoT - Robotics integration project to extend onboard sensors with networked embedded systems for greater operational autonomy and hardware redundancy
- Ongoing work on a situational awareness package using ROS Nodelets and OpenCV to provide remote operators with context-aware visual feedback
- Co-authored a paper on intuitive remote teleoperation leveraging VR motion sensors and affordance templates
- Participated in an intercontinental teleoperation demonstration between UT Austin and Woodside Energy (Perth, Australia)
- Created and tested a virtual reality dual manipulator jogging scheme using the HTC Vive motion controller system
- Conducted feasibility analysis on next-gen ROS networking solutions including 10G fiber tether, WiFi 802.11ax, and 5G modems

Teaching Assistant

Introduction to Computing (UT ECE Dept.)

Aug 2019 - Dec 2019

Austin, Texas U.S.A.

- Created an IDE-like extension for Visual Studio Code for LC3 assembly language, including syntax highlighting, autocomplete, and snippet support: [PaperFanz/lc3-assembly-vscode-ext](#)
- Developed an accompanying assembler with extended pseudo-op features and cross-file assembly in C: [PaperFanz/laser](#)

NanoExplorer Scholar

Human Enabled Robotics Lab

June 2016 - July 2018

Richardson, Texas U.S.A.

- Developed a motion smoothness measurement algorithm for use in a robotic surgery training system using C++, OpenGL, and ROS
- Designed and conducted human subject study assessing effectiveness and robustness compared to existing measures

TECHNICAL SKILLS

System Design

Computer Architecture

Operating Systems

Motion Controls

Virtual Reality

Computer Vision

Embedded Software

Circuit Design

CAD

PROGRAMMING

C/C++

Python

ROS/ROS2

OpenCV

Java

Rust

QT5

Javascript/Typescript

HTML/CSS

Verilog

R

MATLAB

LaTeX

SOFTWARE

Linux

Visual Studio Code

Git

Keil uVision 5

Xilinx Vivado

R Studio

MATLAB

Fusion 360

EasyEDA

REFEREES

Dr. Mitchell W. Pryor, Ph.D

Research Scientist

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Dr. Ramesh Yerraballi, Ph.D

Professor of Instruction

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PUBLICATIONS

Conferences

- Pettinger, Adam et al. (2020). "Reducing the Teleoperator's Cognitive Burden for Complex Contact Tasks Using Affordance Primitives". In: *Proceedings of IROS 2020*. Las Vegas, USA.